



$$\vec{p}_1 = p_{1y} \hat{y}$$

$$\vec{p}_2 = p_{2x} \hat{x}$$

$$\vec{E}_1(r\hat{x}) = \frac{1}{4\pi\epsilon_0} \frac{1}{r^3} [3(\vec{p}_1 \cdot \hat{x})\hat{x} - \vec{p}_1] = \frac{1}{4\pi\epsilon_0} \frac{1}{r^3} (-p_{1y} \hat{y}) = \frac{-p_{1y}}{4\pi\epsilon_0 r^3} \hat{y}$$

$$\vec{E}_2(-r\hat{x}) = \frac{1}{4\pi\epsilon_0} \frac{1}{r^3} [3(\vec{p}_2 \cdot (-\hat{x}))(-\hat{x}) - \vec{p}_2] = \frac{1}{4\pi\epsilon_0} \frac{1}{r^3} [2p_{2x} \hat{x}] = \frac{2p_{2x}}{4\pi\epsilon_0 r^3} \hat{x}$$

$$\vec{N}_1 = \vec{p}_1 \times \vec{E}_2 = \frac{2p_{2x}p_{1y}}{4\pi\epsilon_0 r^3} (\hat{y} \times \hat{x}) = -\frac{2p_{2x}p_{1y}}{4\pi\epsilon_0 r^3} \hat{z}$$

$$\vec{N}_2 = \vec{p}_2 \times \vec{E}_1 = \frac{-p_{2x}p_{1y}}{4\pi\epsilon_0 r^3} (\hat{x} \times \hat{y}) = \frac{p_{2x}p_{1y}}{4\pi\epsilon_0 r^3} \hat{z} = -2\vec{N}_1$$

4.29

$$a) \vec{F}_1 = (\vec{p}_1 \cdot \nabla) \vec{E}_2 = p_{1y} \frac{\partial}{\partial y} \vec{E}_2$$

$$\vec{F}_2 = (\vec{p}_2 \cdot \nabla) \vec{E}_1 = p_{2x} \frac{\partial}{\partial x} \vec{E}_1$$

$$\vec{E}_i(r\hat{r}) = \frac{1}{4\pi\epsilon_0} \frac{1}{r^3} [3(\vec{p}_i \cdot \hat{r})\hat{r} - \vec{p}_i]; \quad \hat{r} = \sin\theta \cos\phi \hat{x} + \sin\theta \sin\phi \hat{y} + \cos\theta \hat{z}$$

$$\vec{F}_1 = \frac{\gamma}{4\pi\epsilon_0 r^3} [3p_{1y} \sin\theta \sin\phi \hat{r} - p_{1y} \hat{y}]$$