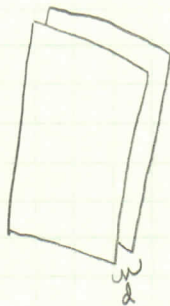


$$\sigma = \frac{Q}{A}$$

a)

$$\vec{E}_{\text{between}} = 0$$



For either plate

$$\vec{E}_{\text{outside}} - \vec{E}_{\text{between}} = \frac{\sigma}{\epsilon_0} \hat{n} \Rightarrow \vec{E}_{\text{outside}} = \frac{\sigma}{\epsilon_0} \hat{n}$$

$$\vec{f} = \frac{1}{2} \sigma (\vec{E}_{\text{outside}} + \vec{E}_{\text{between}}) = \frac{\sigma^2}{2\epsilon_0} \hat{n} = \frac{Q^2}{2\epsilon_0 A^2} \hat{n}$$

2.42

The direction of the force can be determined as follows!



$$\sigma = \frac{Q}{4\pi R^2}$$

$$\vec{A} = \int d\vec{a} = \int R^2 \sin\theta d\theta d\phi \hat{r} = \int R^2 \sin\theta d\theta d\phi (\sin\theta \cos\phi \hat{x} + \sin\theta \sin\phi \hat{y} + \cos\theta \hat{z})$$

Since  $\int_0^{2\pi} \cos\phi d\phi = \int_0^{2\pi} \sin\phi d\phi = 0$ , the  $\hat{x}$  and  $\hat{y}$  components are zero.

$$\vec{A} = R^2 \int_0^{\pi/2} \sin\theta \cos\theta d\theta \int_0^{2\pi} d\phi \hat{z} = 2\pi R^2 \left[ \frac{1}{2} \sin^2\theta \right]_0^{\pi/2} \hat{z} = \pi R^2 \hat{z}$$

Notice this integral is different from its non-vector cousin:  $A = \int da = 2\pi R^2$

$\Rightarrow \vec{A} = \hat{z}$  this is the direction of the force

$$F = \int_S \vec{f} \cdot d\vec{a} \quad d\vec{a} = R^2 \sin\theta d\theta d\phi \hat{n} \quad \vec{f} = \frac{\sigma^2}{2\epsilon_0} \hat{n}$$

$$F = \int_S \frac{\sigma^2}{2\epsilon_0} R^2 \sin\theta d\theta d\phi = \frac{\pi \sigma^2 R^2}{2\epsilon_0} \int_0^{\pi/2} \sin\theta d\theta = -\frac{\pi \sigma^2 R^2}{2\epsilon_0} \cos\theta \Big|_0^{\pi/2} = \frac{\pi \sigma^2 R^2}{2\epsilon_0} = \frac{\pi Q^2 R^2}{2(4\pi R^2)^2 \epsilon_0}$$

$$F = \frac{Q^2}{32\pi\epsilon_0 R^2} \Rightarrow \vec{F} = \frac{Q^2}{32\pi\epsilon_0 R^2} \hat{z}$$

Alternatively, we can think of  $\vec{A} = \pi R^2 \hat{z}$  as the area "seen" by the pressure  $\frac{\epsilon_0}{2} E^2$ . After all,  $\pi R^2$  is simply the projection of the hemisphere onto the  $z$ -axis. Then  $\vec{F} = P\vec{A} = \frac{\epsilon_0}{2} \left(\frac{Q^2}{\epsilon_0^2}\right) \pi R^2 \hat{z} = \frac{Q^2 \pi R^2}{2(4\pi R^2)^2 \epsilon_0} \hat{z} = \frac{Q^2}{32\pi\epsilon_0 R^2} \hat{z}$